

Action = Pattern Data * Timing Data (Limited by TimeSet) * Waveset * Drive

FIG._1

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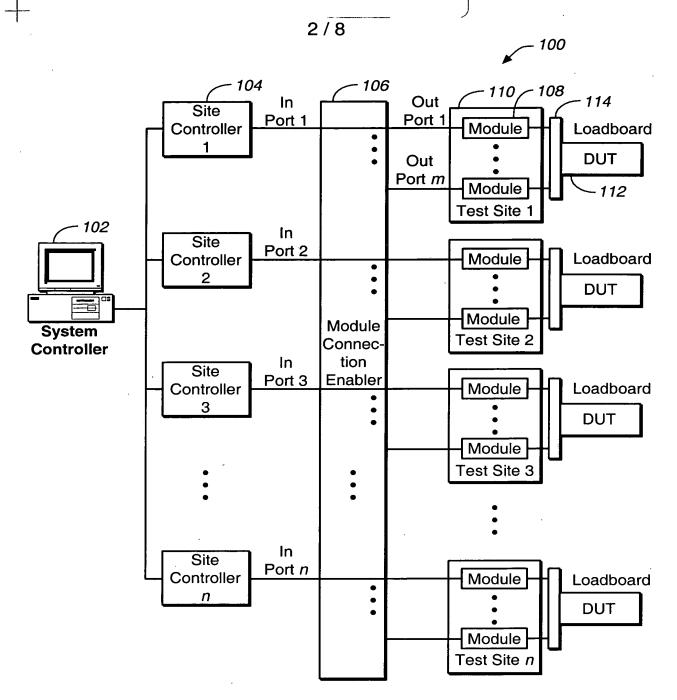
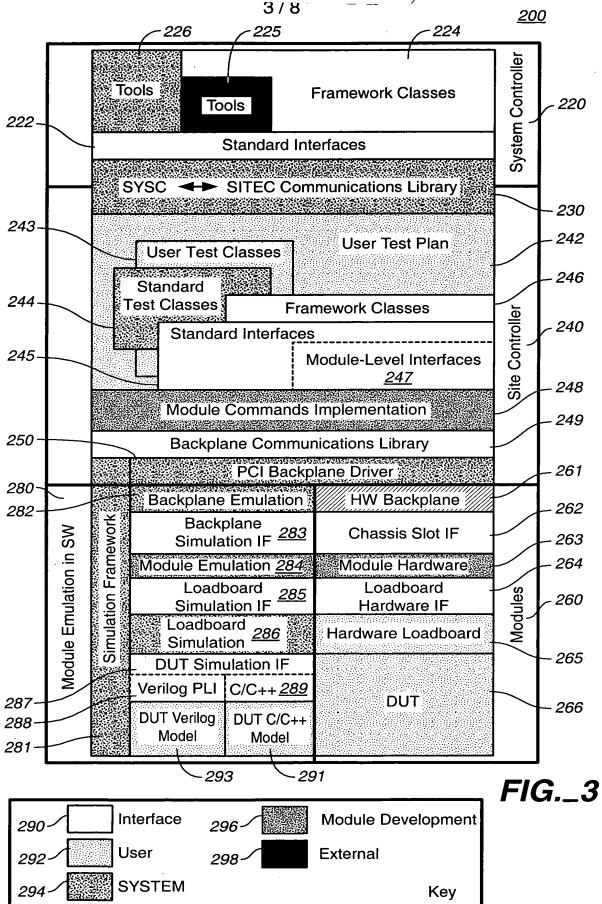


FIG._2

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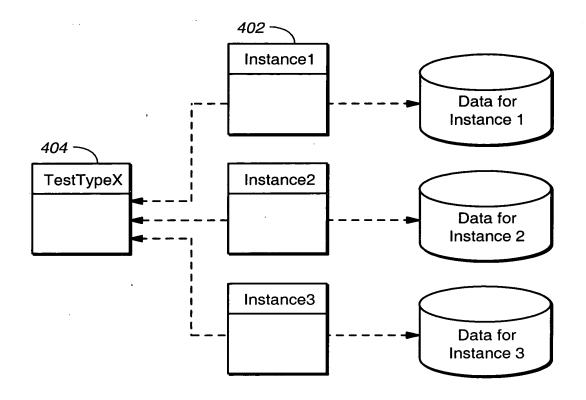
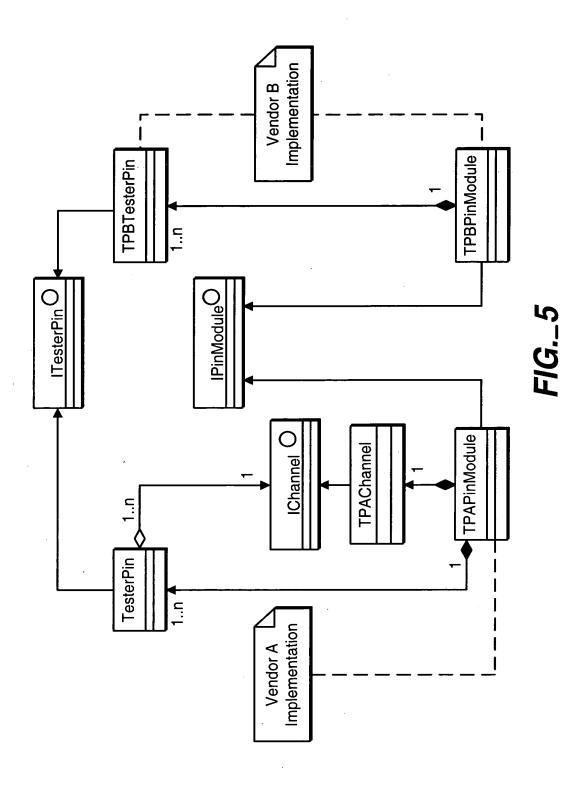


FIG._4

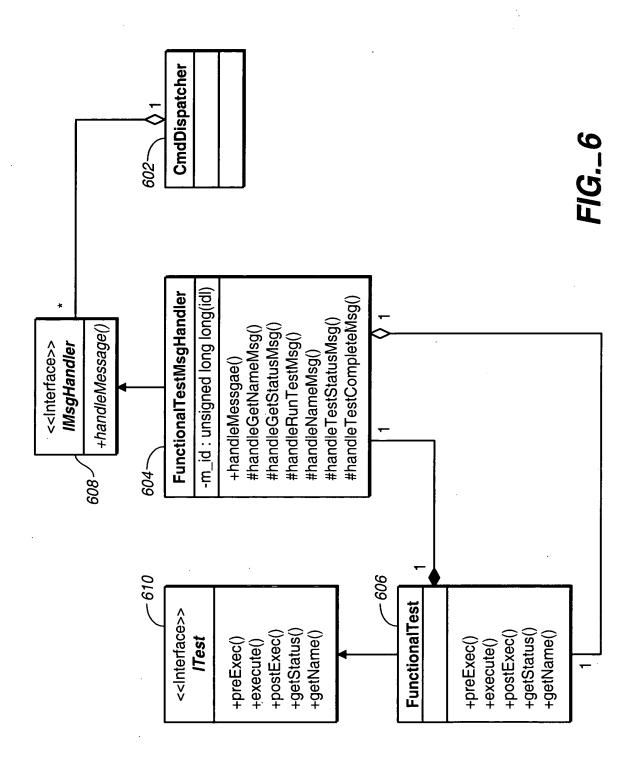
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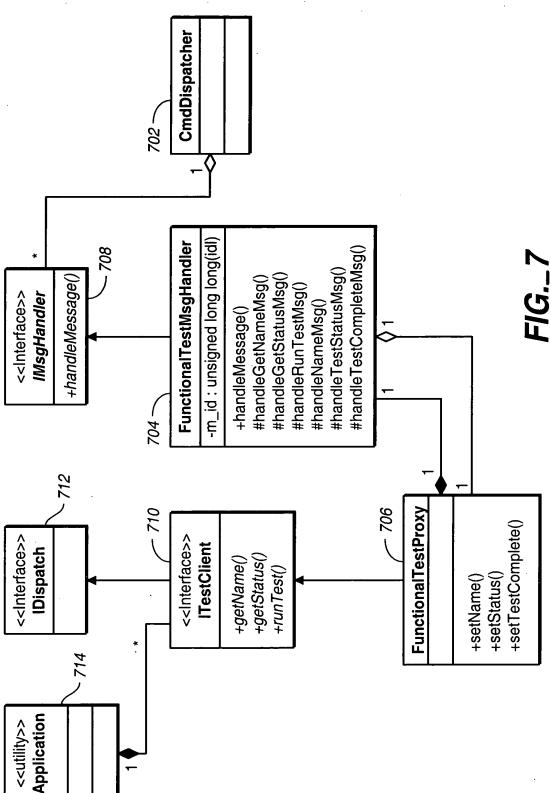


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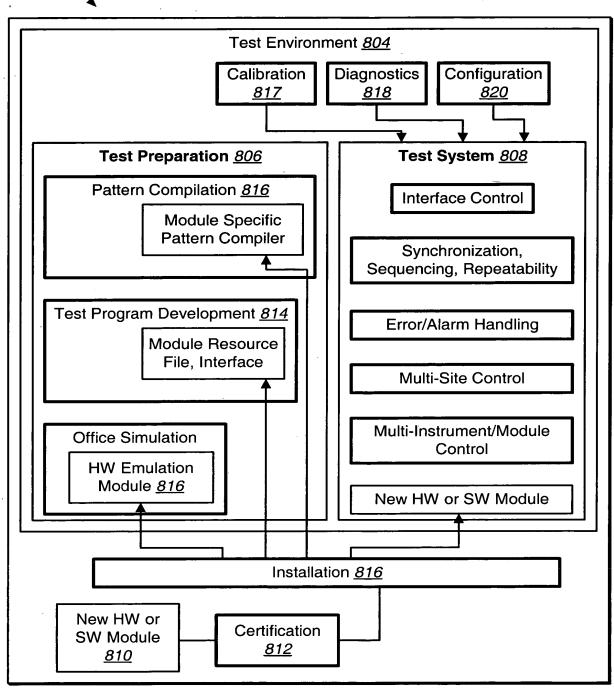


FIG._8